# Generalization of the Group Classification with Application of Elliptic Partial Differential Equations 

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#### Abstract

This research work enhance the generalizing previous result on a one-dimensional nonlinear elliptic partial differential equation. By the use of new techniques of a partial differential equation with the equivalence of group ,class of group and groupoid, we extend the algebraic method of classification of nonlinear partial differential equations. The solution includes the preliminary group, sub algebras, and infinite-dimensional equivalence algebra. This result is examined by the example of Elliptic partial differential equation.


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## 1. Introduction

In this research paper, with concerned ofgroup classification we finding an equivalent equation of a class of differential equation at containing the one or more arbitrary elements. These work are correlated with theoretical physics, which include the maximal number of symmetries from a given class yield and there describe the scientific model of real world problem.

In mathematics, the group classification problem of partial differential equation had been investigated by Sophus Lie's classifications of second-order ordinary differential equations and of second-order linear partial differential equations with two independent variables.

Recently a various novel techniques of group classification have been introduced, which include the algebraic method [ $5,6,13,8,9]$ and advanced modification of the direct method which is called furcate splitting [7, 9, 4]. The algebraic method of group classification applied to the classes of differential equations with the arbitrary elements of functions of several arguments.

The class considered in the literature on group classification, is the most prominent ones are classes of ( $1+1$ )-dimensional evolution equations, $[1,2,3,4,8,14,16,15$,]. There is no coincidence in the field of invariant discretization, numerical schemes for differential equations possessing the same symmetries as the original, undiscretized equations, mostly evolutionary equations [10].

Definition 1.Definition 1. Admissible transformations $T^{1}=\left(\theta^{1}, \emptyset^{1}, \widetilde{\theta^{1}}\right)$ and $T^{2}=\left(\theta^{2}, \emptyset^{2}, \widetilde{\theta^{2}}\right)$ in the class of $\mathscr{L} \mid s$ are called conjugate with respect to the equivalence group $G^{\sim}$ of this class if there exist $\mathcal{T} \in G^{\sim}$ such that $\theta^{2}=\mathcal{T}_{*} \theta^{1}$ and $\emptyset^{2}=\left(w_{*}, \mathcal{T}\right) \mathrm{o} \emptyset^{1} \mathrm{o}\left(w_{*}, \mathcal{T}\right)^{-1} \cdot w_{*}$ denote the projection along with the group coordinate

Definition 2: The class $\mathscr{L} \mid s$ is called normalised if $G^{G^{\sim}}=$ $G^{\sim}$. It is called semi normalised if $G^{f} * G^{G^{\sim}}=G^{\sim}$.

## 2. Main Result

Classification of admissible transformations and group in Elliptic Partial differential equation

Definition: The linear partial differential equation (1) of the second degree defined in some region D in the $x y$ plane is said to be

Hyperbolic of a point $(x y)$ in $D$,
If $\Delta=B^{2}-A C>0$
Parabolic, if $\Delta=B^{2}-A C=0$
Elliptic, if $\Delta=B^{2}-A C<0 \quad$ at the point. It is also satisfy the postulates of group
Closure, Associative, commutative and existence of identity, existence of inverse.
${ }^{*}$ Solution The given P.D.E can be written as

$$
\begin{equation*}
F^{i}\left(u_{t}, u_{x}\right)=r+x^{2} t \tag{1}
\end{equation*}
$$

By the closure axiom of group

$$
a, b \in G \Rightarrow a+b \in G
$$

Then $r, t \in G$

$$
F^{i}\left(u_{t}, u_{x}\right)=r+x^{2} t \in G
$$

By Associative axiom $r, s, t \in G$

$$
(r+s)+\mathrm{t}=\mathrm{r}+(\mathrm{s}+\mathrm{t}) \in G
$$

## Existence of identity

$$
r .1=r, \forall r \in G
$$

## Existence of inverse

$$
r \cdot r^{-1}=1, \forall r \in G
$$

## Commutative Axiom

$(r+s)=(s+r), \forall r, s \in G$
Comparing (1) with $A r+2 B s+C t+f(x, y, u, z, p, q)=0$
We get $A=1, B=0, C=x^{2}$

$$
B^{2}=0, A C=1 \cdot x^{2}=x^{2}
$$

$\therefore B^{2}-A C<0$ at all points where $x \neq 0$.
Hence the given equation is elliptic at all points except on the axis.

Also, the $\lambda$ - quadratic $A \lambda^{2}+2 B \lambda+C=0$ gives
$\lambda^{2}+x^{2}=0$ so that $\lambda= \pm i x$.
Hence $\frac{d y}{d x}+\lambda_{1}=0$ and $\frac{d y}{d x}+\lambda_{2}=0$ becomes

$$
\frac{d y}{d x}+i x=0 \text { and } \frac{d y}{d x}-i x=0
$$

Solution Thegiven P.D.E can be written as

$$
\begin{equation*}
F^{i}\left(u_{t}, u_{x}\right)=r+x^{2} t \tag{1}
\end{equation*}
$$

Comparing (1) with $A r+2 B s+C t+f(x, y, u, z, p, q)=0$

$$
\frac{d y}{d x}+i x=0 \text { and } \frac{d y}{d x}-i x=0
$$

Solving for $\alpha, \beta$, we get

$$
\begin{gathered}
\alpha=y \text { and } \beta=\frac{1}{2} x^{2} \\
p=\frac{\partial z}{\partial x}=\frac{\partial z}{\partial \alpha} \cdot \frac{\partial \alpha}{\partial x}+\frac{\partial z}{\partial \beta} \cdot \frac{\partial \beta}{\partial x}=x \frac{\partial z}{\partial \beta} \\
q=\frac{\partial z}{\partial y}=\frac{\partial z}{\partial \alpha} \cdot \frac{\partial \alpha}{\partial y}+\frac{\partial z}{\partial \beta} \frac{\partial \beta}{\partial y}=\frac{\partial z}{\partial \alpha} \operatorname{so} \frac{\partial}{\partial y}=\frac{\partial}{\partial \alpha} \\
r=\frac{\partial}{\partial x}\left(\frac{\partial z}{\partial x}\right)=\frac{\partial}{\partial x}\left(x \frac{\partial z}{\partial \beta}\right) \\
=1 \cdot \frac{\partial z}{\partial \beta}+x \frac{\partial}{\partial x}\left(\frac{\partial z}{\partial \beta}\right) \\
=\frac{\partial z}{\partial \beta}+x\left[\frac{\partial}{\partial \alpha}\left(\frac{\partial z}{\partial \beta}\right) \frac{\partial \alpha}{\partial x}+\frac{\partial}{\partial \beta}\left(\frac{\partial z}{\partial \beta}\right) \frac{\partial \beta}{\partial x}\right]=\frac{\partial z}{\partial \beta}+x^{2} \frac{\partial^{2} z}{\partial \beta^{2}} \\
t=\frac{\partial}{\partial y}\left(\frac{\partial z}{\partial y}\right)=\frac{\partial}{\partial \alpha}\left(\frac{\partial z}{\partial \alpha}\right)=\frac{\partial^{2} z}{\partial \alpha^{2}} .
\end{gathered}
$$

Putting these values of $r$ and $t$ in (1), we get

$$
\frac{\partial z}{\partial \beta}+x^{2} \frac{\partial^{2} z}{\partial \beta^{2}}+x^{2} \frac{\partial^{2} z}{\partial \alpha^{2}}=0
$$

or

$$
\frac{\partial^{2} z}{\partial \alpha^{2}}+\frac{\partial^{2} z}{\partial \beta^{2}}=\frac{-1}{2 \beta} \frac{\partial z}{\partial \alpha}
$$

canonical form of Elliptic Partial differential Equation $T^{1}=\left(p^{1}, q^{1}, r^{1}, t^{1}\right)$ and $T^{2}=\left(p^{2}, q^{2}, r^{1}, t^{1}\right)$ is this class of $\mathscr{L} \mid S$ are called conjugate with respect to the equivalence group $G^{\sim}$ if there exist $T \in G^{\sim}$ such that $p^{2}=\mathcal{T}_{*} P^{1}$ and $q^{2}=\left(w_{*}, T\right) \mathrm{o} Q^{1} \mathrm{o}\left(w_{*}, \mathcal{T}\right)^{-1} \cdot w_{*}$ denote the projection along with the coordinate

It satisfies the condition of admissible transformation of partial differential equations.

Result: The Elliptic partial differential equation is satisfying the all postulates of group Axiom.

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