

Framework for Natural Neuron Network Modeling: The Jneopallium Approach

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Abstract: *This article presents Jneopallium, a robust framework designed for modeling natural neuron networks with varying levels of detail. Drawing inspiration from historical advancements in neuropsychology and artificial neural networks, Jneopallium offers a modular and flexible approach to simulate neural structures. It allows for the definition of multiple signal types, neuron types, and processing logic, enabling detailed replication of natural cognitive processes. Utilizing Java for implementation, Jneopallium provides an intuitive interface for researchers to define neural architectures, processing rules, and input/output logic. This framework aims to bridge the gap between neurobiology and computer science, supporting applications in robotics, AI development, and neuroscience research. The paper details the functional, structural, and IO logic definition processes, showcasing the framework's versatility and potential for advancing neural network modeling.*

Keywords: Neuron network modeling, Jneopallium, neural architecture, signal processing, neurobiology simulation

1. Introduction

Psychologist Donald Olding Hebb performed the first theoretical attempt to describe a learning algorithm based on natural neuron nets in the 1940s [1]. Farley and Wesley Allison Clark implemented the Hebbian network in code in 1954 at MIT [2]. Psychologist Frank Rosenblatt published the idea of perceptron in 1958 [3]. In 1982 neurophysiologically inspired self-organizing maps were described by Teuvo Kohonen [4] [5]. Neocognitron has been designed by Kunihiko Fukushima in 1980 [6]. This invention has been inspired by the visual cortex research of neuropsychologists David Hunter Hubel and Torsten Nils Wiesel [7].

It is safe to say that a lot of core artificial neuron network algorithms are low-detailed models of natural neuron networks and/or their parts.

2. Problem Formalization

Accordingly, to the previous section, it seems logical to have some unified framework for building custom depth detailization natural neuron networks modeling framework. After high-level research of neurobiology and comparison with current artificial neuron network algorithms, I have formed the next statements:

- 1) Neurons can process 2 classes of signals: biochemical and bioelectrical. Differences in bioelectrical and biochemical signal propagation are significant.
- 2) Different signals have different propagation times.
- 3) The set of neuron receptors defines signals it can process and structure. The set of receptors in different neuron types is different.
- 4) Cognitive processes are time-related.

The modelling framework should be able to:

- 1) Define different types of signals.
- 2) Define a neuron that able to process multiple signal types with different processing logic for each signal type.
- 3) Define different types of neurons.
- 4) Define relative processing rates for 2 classes of signals.

- 5) Define the relative processing rate for each type of signal.

These requirements have been used for jneopallium implementation.

Natural neuron net modeling process

High-level architecture

Jneopallium is a set of interfaces and implementations that separate neuron network processing logic from actual neuron and signal types in a similar way collections separate storage logic from actual object types that it stores with the help of generics. I have chosen java for implementation because it is suitable for interfaces and generic usage and provides some sort of type safety. All jneopallium code placed in github [8] and gitlab [9] repositories are distributed by BSD 3 – Clause License.

To build a model user should define signal types, neuron types, input sources, and output collector classes. Then describe the neuron network structure, specify technical information in the configuration file, and launch jneopallium with the specified path to the user-defined code jar, neuron network structure, and configuration file. The second reason why I have chosen java for implementation is because it can load user-defined code in runtime. Jneopallium can work in 3 modes: local, cluster http and cluster grpc. Grpc allows to run jneopallium on FPGAs. For this article, I have split the modeling process into 3 parts: functional logic definition, structural logic definition, and io logic definition. The following 3 sub-sections describe the modeling process.

Functional Logic Definition

The modeling process starts with the signal definition. The user should define all signals in the system and the weight object that will be used for learning. The next step is neuron interface definitions. Each processing mechanism should have a separate neuron interface that extends the basic INeuron interface. The third step is signal processor

Volume 13 Issue 7, July 2024

Fully Refereed | Open Access | Double Blind Peer Reviewed Journal

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implementation. Signal processors should implement an `ISignalProcessor` interface parametrized by signal process and neuron interface that has suitable mechanisms for processing. Then user should implement neurons by extending the `Neuron` class and implementing the interface or interfaces defined in step 2. Multiple inheritance via interface implementation allows the user to implement neurons with multiple processing mechanisms that can process different signal types. Also, the neuron has `Axon` class and `Dendrites` class. `Dendrites` encapsulate input addresses (input source name or layer id and neuron id), signal types, and weights. These weights apply to input signals and should be used in the learning process. `Axon` encapsulate output addresses (layer id and neuron id) signal type and weight. These weights apply to output signals and also should be used in the learning process.

To show an example of a modeling process I have defined 4 signals and 3 neurons in the separate test branch [10]. `IntSignal` class represents a signal described with an integer value. `DoubleSignal` class represents signal described with double value. `IntProcessor` and `DoubleProcessor` classes describe the processing logic for these signals. `NeuronIntField` and `NeuronWithDoubleField` interfaces describe neurons with an internal structure that allows to process `IntSignal` and `DoubleSignal` respectively. `NeuronC` and `NeuronB` are neuron implementations that process just one type of signal. `NeuronA` is neuron that can process both signals i. e. it has 2 receptors.

Structural logic definition

After all functional model parts have been defined user should define the structure of the neural network. I recommend using a statistical approach i. e. finding the probability appearance of each neuron on each layer. It allows for modeling horizontal structure. In order to define what neuron order on layers can be user should implement `NeighboringRules` interface. This feature allows for the modeling of vertical neuron structure.

Structure modeling examples are placed here [11]. Structure modeling was performed with the help of `NeuronNetStructureGenerator`. It requires hash map with layer sizes, hash map with statistical properties for each neuron type, a list of `NeighboringRules`, and class that implements `IConnectionGenerator`. `IConnectionGenerator` describes how to connect neurons.

I/O logic definition

I/O logic describes input sources and output destinations. The neuron net can have multiple inputs. To define the input source user should implement the interface `IInitInput`. Each input has a default processing frequency that shows how often signals from the input will be propagated to neurons. Processing frequency can be modified with the help of signal sending to `CycleNeuron` (more details about it will be in the next sub - section). The way how input signals propagate to neurons should be described with the help of the implementation of `InputInitStrategy` interface. Each input source can have a separate `InputInitStrategy`. If the input is another neuron network output, signals can be send to the

neuron network. In this case, input should be implemented `INeuronNetInput` interface. This feature can be useful to build modular models in order to simplify learning. To define the output destination user should implement `IOutputAggregator` interface. The example of i/o logic definition is placed in this package [12].

Signals processing frequency

The signal processing frequency is defined by 2 processing loops. Fast loop processes every processing iteration and slow loop processes once in n iterations of the fast loop. The n is defined in `CycleNeuron` and can be changed with the help of sending the signal to layer with id -2147483648 and neuron with id 0. Each signal type and input source have `ProcessingFrequency` that is described with an integer field loop and long field epoch. Signal with `ProcessingFrequency` loop 1 will be processed each time of fast loop processing, with value 2 once in 2 processing, with value 3 once in 3 processing, etc. `ProcessingFrequency` epoch uses the same logic but for a slow loop. The following code describes all possible signal to `CycleNeuron` and processing logic [13].

Layer sizing

Layer can be sized with the help of signal sending to `LayerManipulatingNeuron`. It is situated on each layer with id -9 223 372 036 854 775 808 and can create and delete neurons. Here You can find the list of signal and processing logic [14].

Additional features

There exists the ability to define any number of discriminators for neuron networks. It can be used to implement GAN. Also, the user can store and extract parameters in layers.

Configuration files

Examples of configuration files can be found here [15].

Application, monetization, competitors

Application

Models built with the help of `jneopallium` can be used for robotics. The output and input are defined by the user so it can directly communicate with controllers. I expect that general AI can be implemented with such an approach.

Also, such models can be used for company management in environments with different volatility signals and metrics.

It can be used for natural neuron network modeling especially when should model control structure and structure with different deviations.

It can be used for autonomous mission control when the connection latency to high and exists high conditions and mission flow uncertainty.

Monetization

Jneopallium has a few scenarios of monetization. The first one is through building models for different products. The other way of monetization is providing hosting services the same way cloud providers do with Spark. The third way is FPGAs optimization for a model.

Competitors

The closest competitor for jneopallium is NEURON Simulator [16] [17] and CoreNeuron [18]. It allows the building of highly detailed models of natural neuron networks. The main difference is that jneopallium allows users to choose the level of detailization. Jneopallium's main purpose is to be a bridge between neurobiology and computer science. NEURON Simulator and CoreNeuron main purpose is to build an exact copy of a natural neuron network.

Thank You for your attention.

Competitors

Jneopallium represents a significant step forward in the modeling of natural neuron networks, offering a versatile and scalable framework that integrates the complexities of neurobiology with the precision of computer science. By allowing users to define various neuron and signal types, processing logic, and neural structures, Jneopallium facilitates the creation of detailed and functional neural models. Its potential applications span across robotics, artificial intelligence, and neuroscience research, providing a valuable tool for exploring and understanding cognitive processes. As a bridge between the fields of neurobiology and computer science, Jneopallium stands out for its ability to simulate natural neural networks with customizable levels of detail, promising advancements in both theoretical and practical domains.

Author's Contributions: Architecture design, code implementation, testing – Dmytro Rakovskyi

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